SYSMAC CJ-series CJ1M CPU Units (with Built-in I/O)

CJ1M-CPU2

CSM_C.I1M-CPU2_DS_E_4_1

Compact, Applications-oriented Controllers with Built-in Pulse I/O for High Potential

- The compact, high-potential SYSMAC CJ1M PLCs provide built-in pulse I/O for high-precision performance
- Pulse I/O for two axes to achieve higher machine precision.



CJ1M-CPU21

Features

Two 100-kHz Pulse Outputs

- Use special instructions to easily implement various types of positioning, such as positioning with trapezoidal acceleration/deceleration, positioning with different acceleration/deceleration rates, and triangular control.
- Combine positioning instructions to handle many different applications, such as interrupt feeding and target position changes during positioning.
- Pulse startup is as fast as 46 μ s and is 70 μ s even for trapezoidal acceleration/deceleration.

Two Pulse Inputs

• Two high-speed counters and four interrupt inputs are also built in. The high-speed counters operate at up to 100 kHz for single-phase and 50 kHz for differential-phase operation. These inputs enable controlling with high-speed response.

Use the Rich Lineup of CJ1 Units

- Handle a wide range of applications with the rich lineup of CJ1 Units, including Ethernet and other Communications Units and Analog I/O Units.
- Easier maintenance is also possible using Memory Cards.

Ordering Information

International Standards

- The standards are abbreviated as follows: U: UL, U1: UL(Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, and CE: EC Directives.
- Contact your OMRON representative for further details and applicable conditions for these standards.

CJ1M CPU Units (with Built-in I/O)

Duo	duat mana			Specifications	Current consumption (A)		Model	Chandarda		
Product name		I/O capacity/ Mountable Units (Expansion Racks)	Program capacity	Data memory capacity	LD instruction execution time	Built-in I/O	5 V	24 V	Model	Standards
	Built-in I/O (See note 2.)	640 points/20 Units (1 Expansion Racks max.)	20K steps	32K words (DM: 32K words, EM: None)		10 inputs and	0.64 (See note 1.)	-	CJ1M-CPU23 (See note 3.)	
CJ1M CPU Units		320points/10 Units (No Expansion Rack)	10K steps		0.1 μs	6 outputs, 2 counter inputs, 2	0.64 (See note 1.)	_	CJ1M-CPU22 (See note 3.)	UC1, N, L, CE
		160 points/10 Units (No Expansion Rack)	5K steps			pulse outputs	0.64 (See note 1.)	-	CJ1M-CPU21 (See notes 2 and 3.)	

- Note: 1. Current consumptions include current for a Programming Console. Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.
 - 2. Some of the specifications for the low-end CJ1M CPU Units (CJ1M-CPU11(-ETN)/21) are different from the specifications for the other CJ1M CPU Units (CJ1M-CPU12(-ETN)/13(-ETN)/22/23), including the specifications for overhead time, pulse start time, the number of subroutines and jumps, the number of scheduled interrupt tasks, and the number of PWM outputs. For details, refer to the SYSMAC CJ Series Programmable Controllers Operation Manual (Cat. No. 393) and the SYSMAC CJ Series Built-in I/O Operation Manual (Cat. No. 395).
 - 3. The connector for built-in I/O in the CJ1M-CPU21/22/23 is not included. Purchase one of the connectors or connector cables in the following table separately.

Connector Cables for Built-in I/O in CJ1M-CPU2□ CPU Units

The connector for built-in I/O in the CJ1M-CPU21/22/23 is not included.

Purchase one of the connectors or connector cables in the following table separately.

For details, refer to Built-in I/O MIL Connector Wiring Methods.

Product name	Specif	Model	Standards		
	MIL Flat Cable Connectors *1		40-pin Pressure- welded Connectors	XG4M-4030-T	
Applicable Connectors	MIL Loose Wire Connectors *2		40-pin Crimped Connectors	XG5N-401 *4	_
	Crimp Contacts for XG5N *3	The state of the s	Loose contacts	XG5W-0232	
		The state of the s	Reel contacts	XG5W-0232-R	
	Manual Crimping Tool for XG5N			XY2B-7007	
	Phillips screw (M3 screw terminals,40-ter	rminals)		XW2R-J40G-T	
Connector-Terminal Block Conversion Units	Slotted screw (M3 European type ,40-ter	minals)		XW2R-E40G-T	
	Push-in spring (Clamp 40-terminals)			XW2R-P40G-T	-
			Cable length: 1 m	XW2Z-100K	†
Cable for Connector Torreits -1			Cable length: 1.5 m	XW2Z-150K	<u> </u>
Cable for Connector-Terminal Block Conversion Unit			Cable length: 2 m	XW2Z-200K	
2.23 2011/01/01/01/01	•		Cable length: 3 m	XW2Z-300K	
			Cable length: 5 m	XW2Z-500K	

- *1. Socket and Stain Relief set
- *2. Crimp Contacts (XG5W-0232) are sold separately.
- *3. Applicable wire size is 28 to 24 AWG.
 - For applicable conductor construction and more information, visit the OMRON website at www.ia.omron.com.
- ***4.** Crimp Contacts are also required.

Note: Minimum ordering quantity for loose contacts is 100 pieces and for reel contacts is 1 reel (10,000 pieces).

Product name		Model	Standards		
	Servo Relay Unit for 1 axi	XW2B-20J6-8A			
Servo Relay Units	Servo Relay Unit for 2 ax	es		XW2B-40J6-9A	_
		Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A33	
	OMNUC G Series		Cable length: 1 m	XW2Z-100J-A33	
	CIVILVOO Q GENES	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B31	
			Cable length: 2 m	XW2Z-200J-B31	
	SMARTSTEP2	Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A33	
			Cable length: 1 m	XW2Z-100J-A33	
		Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B32	
			Cable length: 2 m	XW2Z-200J-B32	
Cables for Servo Relay Units		Cable for CJ1M CPU Unit	Cable length: 1 m	XW2Z-100J-A26	
Cables for Servo netay offits	SMARTSTEP Junior	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B17	
			Cable length: 2 m	XW2Z-200J-B17	
		Cable for CJ1M CPU Unit	Cable length: 1 m	XW2Z-100J-A26	
	SMARTSTEP A Series	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B5	
			Cable length: 2 m	XW2Z-200J-B5	
		Cable for CJ1M CPU Unit	Cable length: 0.5 m	XW2Z-050J-A27	
	OMNUC W Series		Cable length: 1 m	XW2Z-100J-A27	
	Olvinoc w Series	Servo Driver Connecting Cables	Cable length: 1 m	XW2Z-100J-B4	
			Cable length: 2 m	XW2Z-200J-B4	

Accessories

The following accessories come with CPU Unit:

Item	Specification
Battery	CJ1W-BAT01
End Cover	CJ1W-TER01 (necessary to be mouned at the right end of CPU Rack)
End Plate	PFP-M (2 pcs)
Serial Port (RS-232C) Connector	Connector set for serial port connection (D-SUB 9-pin male connector)

Specifications

Common Specifications

	Item		Specificat	ions						
Control me	ethod	Stored program								
I/O control	method	Cyclic scan and immediate processing are both possible.								
Programm	ing	LD (Ladder), SFC (Sequential Function Chart), ST (Structured Text), Mnemonic								
CPU proce	essing mode	Normal Mode or Peripheral Servicing Priority Mode								
Instruction	length	1 to 7 steps per instruction	on							
Ladder ins	structions	Approx. 400 (3-digit func	tion codes)							
Execution	time		Basic instructions: 0.10 μs min. Special instructions: 0.15 μs min.							
Overhead	time		CJ1M CPU Units (CPU22/23): 0.5 ms min. CJ1M CPU Units (CPU21): 0.7 ms min.							
Unit conne	ection method	No Backplane: Units con	nected directly to each other.							
Mounting I	method	DIN Track (screw mount	ing not possible)							
Maximum I Units	number of connectable	Total of 20 Units in the S	ystem, including 10 Units on CPU Rack	and 10 Units on one Expansion	on Rack.					
Maximum Racks	number of Expansion	CJ1M CPU Units (CPU 1 max. (An I/O Contro CJ1M CPU Units (CPU Expansion is not poss	I Unit is required on the CPU Rack and a U11/12/21/22):	n I/O Interface Unit is require	d on the Expansion Rack.)					
Number of	i tasks	Note: 1. Cyclic tasks a 2. The following Power OFF in Scheduled int I/O interrupt ta	fined as cyclic tasks called "extra cyclic to tre executed each cycle and are controlle 4 types of interrupt tasks are supported. terrupt tasks: 1 max. errupt tasks: 2 max.							
Interrupt types		Scheduled Interrupts: Interrupts generated at a time scheduled by the CPU Unit's built-in timer. (See note. 1) I/O Interrupts: Interrupts from Interrupt Input Units. Power OFF Interrupts (See note 2.): Interrupts executed when the CPU Unit's power is turned OFF. External I/O Interrupts: Interrupts from the Special I/O Units or CPU Bus Units. Note: 1. Scheduled interrupt time interval is 0.5 ms to 999.9 ms (in increments of 0.1 ms), 1 ms to 9,999 ms (in increments of 10 ms), or 10 ms to 99,990 ms (in increments of 10 ms) 2. Not supported when the CJ1W-PD022 Power Supply Unit is mounted.								
Calling sul than one ta	broutines from more ask	Supported (called "globa	l subroutines").							
	plocks (CPU Unit with on 3.0 or later only)	Languages in function bl	ock definitions: ladder programming, stru	ctured text						
	I/O Area		O 007915 (80 words from CIO 0000 to C ord can be changed from the default (CIC Basic I/O Units.							
	Link Area	3,200 (200 words): CIO - Link bits are used for dat								
	CPU Bus Unit Area	6,400 (400 words): CIO 150000 to CIO 189915 (words CIO 1500 to CIO 1899) CPU Bus Unit bits store the operating status of CPU Bus Units. (25 words per Unit, 16 Units max.)								
	Special I/O Unit Area	15,360 (960 words): CIO Special I/O Unit bits are a Note: Special I/O Units Example:CJ1W-A								
	Serial PLC Link Area	1,440 (90 words): CIO 3	10000 to CIO 318915 (words CIO 3100 to	CIO 3189)						
			320000 to CIO 379915 (words CIO 3200 ted to Slaves for DeviceNet Unit remote I/		The CIO Area can be used as work bits if the bits are not					
CIO (Core I/O)		Fixed allocation setting 1	Outputs: CIO 3200 to CIO 3263 Inputs: CIO 3300 to CIO 3363		used as shown here.					
Area		Fixed allocation setting 2	Outputs: CIO 3400 to CIO 3463 Inputs: CIO 3500 to CIO 3563							
	B	Fixed allocation setting 3	Outputs: CIO 3600 to CIO 3663 Inputs: CIO 3700 to CIO 3763							
	DeviceNet Area		allocated to the Master function even whe	n the DeviceNet Unit is used						
		Fixed allocation setting 1	Outputs: CIO 3370 (Slave to Master) Inputs: CIO 3270 (Master to Slave)							
		Fixed allocation setting 2	Outputs: CIO 3570 (Slave to Master) Inputs: CIO 3470 (Master to Slave)							
		Fixed allocation setting 3	Outputs: CIO 3770 (Slave to Master) Inputs: CIO 3670 (Master to Slave)							
	Internal I/O Area	37,504 (2,344 words): Cl	120000 to CIO 149915 (words CIO 1200 IO 380000 to CIO 614315 (words CIO 38 a are used as work bits in programming to	00 to CIO 6143)	hey cannot be used for external					

Item	Specifications
Work Area	8,192 bits (512 words): W00000 to W51115 (W000 to W511) Controls the programs only. (I/O from external I/O terminals is not possible.) Note: When using work bits in programming, use the bits in the Work Area first before using bits from other areas.
Holding Area	8,192 bits (512 words): H00000 to H51115 (H000 to H511) Holding bits are used to control the execution of the program, and maintain their ON/OFF status when the PLC is turned OFF or theoperating mode is changed. Note: The Function Block Holding Area words are allocated from H512 to H1535. These words can be used only for the function block instance area (internally allocated variable area).
Auxiliary Area	Read only: 7,168 bits (448 words): A00000 to A44715 (words A000 to A447) Read/write: 8,192 bits (512 words): A44800 to A95915 (words A448 to A959) Auxiliary bits are allocated specific functions.
Temporary Area	16 bits (TR0 to TR15) Temporary bits are used to temporarily store the ON/OFF execution conditions at program branches.
Timer Area	4,096: T0000 to T4095 (used for timers only)
Counter Area	4,096: C0000 to C4095 (used for counters only)
DM Area	32 Kwords: D00000 to D32767 Used as a general-purpose data area for reading and writing data in word units (16 bits). Words in the DM Area maintain their status when the PLC is turned OFF or the operating mode is changed. Internal Special I/O Unit DM Area: D20000 to D29599 (100 words × 96 Units) Used to set parameters for Special I/O Units. CPU Bus Unit DM Area: D30000 to D31599 (100 words × 16 Units) Used to set parameters for CPU Bus Units.
EM Area	None
Index Registers	IR0 to IR15 Store PLC memory addresses for indirect addressing. Index registers can be used independently in each task. One register is 32 bits (2words). Setting to use index registers either independently in each task or to share them between tasks.
Task Flag Area	32 (TK0000 to TK0031) Task Flags are read-only flags that are ON when the corresponding cyclic task is executable and OFF when the corresponding task is not executable or in standby status.
Trace Memory	4,000 words (trace data: 31 bits, 6 words)
File Memory	Memory Cards: Compact flash memory cards can be used (MS-DOS format). OMRON Memory Cards can be used.

Function Specifications

Item	Specifications					
Constant cycle time	1 to 32,000 ms (Unit: 1 ms)					
Cycle time monitoring	Possible (Unit stops operating if the cycle is too long): 10 to 40	,000 ms (Unit: 10 ms)				
I/O refreshing	Cyclic refreshing, immediate refreshing, refreshing by IORF(09 IORF(097) refreshes I/O bits allocated to Basic I/O Units and S The CPU BUS UNIT I/O REFRESH (DLNK(226)) instruction ca and DM Areas whenever required.					
Timing of special refreshing for CPU Bus Units	Data links for Controller Link Units and SYSMAC LINK Units, remote I/O for DeviceNet Units, and other special refreshing for CPU Bus Units is performed at the following times: I/O refresh period and when the CPU BUS UNIT I/O REFRESH (DLNK(226)) instruction is executed.					
I/O memory holding when changing operating modes	Depends on the ON/OFF status of the IOM Hold Bit in the Aux	Depends on the ON/OFF status of the IOM Hold Bit in the Auxiliary Area.				
Load OFF	All outputs on Output Units can be turned OFF when the CPU	Unit is operating in RUN, MONITOR, or PROGRAM mode.				
Timer/Counter PV refresh method	BCD or binary (CX-Programmer Ver. 3.0 or higher).					
Input response time setting	Time constants can be set for inputs from Basic I/O Units. The time constant can be increased to reduce the influence of noise and chattering or it can be decreased to detect shorter pulses on the inputs.					
Mode setting at power-up	Possible (By default, the CPU Unit will start in RUN mode if a Programming Console is not connected.)					
Flash memory	backup and restore.) • CPU Units with unit version 3.0 or later only:					
	Automatically reading programs (autoboot) from the Memory Card when the power is turned ON.	Possible				
	Program replacement during PLC operation	Possible				
Memory Card functions	Format in which data is stored in Memory Card	User program: Program file format PLC Setup and other parameters: Data file format I/O memory: Data file format (binary format), text format, or CSV format				
	Functions for which Memory Card read/write is supported	User program instructions, Programming Devices (including CX-Programmer and Programming Consoles), Host Link computers, AR Area control bits, easy backup operation				
Filing	Memory Card data and the EM (Extended Data Memory) Area	can be handled as files.				
Debugging	Control set/reset, differential monitoring, data tracing (scheduled, each cycle, or when instruction is executed), instruction error tracing, storing location generating error when a program error occurs.					

Item	Specifications						
Online editing	When the CPU Unit is in MONITOR or PROGRAM mode, multiple program sections ("circuits") of the user program can be edited together. This function is not supported for block programming areas. (With the CX-Programmer is used, multiple program sections of the user program can be edited together. When a Programming Console is used, the program can be edited in mnemonics only.)						
Program protection	Overwrite protection: Set using DIP switch. Copy protection: Password set using CX-Programmer or Programming Consoles.						
Error check	User-defined errors (i.e., user can define fatal errors and non-fatal errors) The FPD(269) instruction can be used to check the execution time and logic of each programming block. FAL and FALS instructions can be used with the CJ1M CPU Units to simulate errors.						
Error log	Up to 20 errors are stored in the error log. Information includes the error code, error details, and the time the error occurred. A CJ1M CPU Unit can be set so that user-defined FAL errors are not stored in the error log.						
Serial communications	Built-in peripheral port: Programming Device (including Programming Console) connections, Host Links, NT Links Built-in RS-232C port: Programming Device (excluding Programming Console) connections, Host Links, no-protocol communications, NT Links, Serial Gateway (Compoway/F master)						
	Serial Communications Unit (sold separately): Protocol macros, Host Links, NT Links, Modbus-RTU slave, No-protocol, Serial Gateway (Compoway/F master, Modbus master)						
Clock	Provided on all models. Accuracy: Ambient temperature						
Power OFF detection time	AC Power Supply Unit: 10 to 25 ms (not fixed) DC Power Supply Unit PD025: 2 to 5 ms; PD022: 2 to 10 ms						
Power OFF detection delay time	0 to 10 ms (user-defined, default: 0 ms) Note: Not supported when the CJ1W-PD022 Power Supply Unit is mounted.						
Memory protection	Held Areas: Holding bits, contents of Data Memory and Extended Data Memory, and status of the counter Completion Flags and present values. Note: If the IOM Hold Bit in the Auxiliary Area is turned ON, and the PLC Setup is set to maintain the IOM Hold Bit status when power to the PLC is turned ON, the contents of the CIO Area, the Work Area, part of the Auxiliary Area, timer Completion Flag and PVs, Index Registers, and the Data Registers will be saved for up to 20 days.						
Sending commands to a Host Link computer	FINS commands can be sent to a computer connected via the Host Link System by executing Network Communications Instructions from the PLC.						
Remote programming and monitoring	Host Link communications can be used for remote programming and remote monitoring through a Controller Link, Ethernet, DeviceNet, or SYSMAC LINK network.						
Communicating across network levels	Remote programming and monitoring from Support Software and FINS message communications can be performed across different network levels, even for different types of network. Pre-Ver. 2.0: Three levels Version 2.0 or later: Eight levels for Controller Link and Ethernet networks (See note.), three levels for other networks. Note: To communicate across eight levels, the CX-Integrator or the CX-Net in CX-Programmer version 4.0 or higher must be used to set the routing tables.						
Storing comments in CPU Unit	I/O comments can be stored as symbol table files in the Memory Card, EM file memory, or comment memory (see note). Note: Comment memory is supported for CX-Programmer version 5.0 or higher and CS/CJ-series CPU Units with unit version 3.0 or later only.						
Program check	Program checks are performed at the beginning of operation for items such as no END instruction and instruction errors. CX-Programmer can also be used to check programs.						
Control output signals	RUN output: The internal contacts will turn ON (close) while the CPU Unit is operating (CJ1W-PA205R).						
Battery life	Battery Set for CJ1M CPU Units: CJ1W-BAT01						
Self-diagnostics	CPU errors (watchdog timer), I/O bus errors, memory errors, and battery errors.						
Other functions	Storage of number of times power has been interrupted. (Stored in A514.)						

I/O Specifications of CJ1M CPU Units (CJ1M-CPU21/22/23)

- CJ1M-CPU2 CPU Units have 10 built-in inputs and 6 built-in outputs.
- The 10 inputs can be used as general-purpose inputs, interrupt inputs, quick-response inputs, high-speed counters, or origin search origin input signals.
- The 6 outputs can be used as general-purpose outputs, pulse outputs, or origin search deviation counter reset outputs.

Data Area Allocations for Built-in I/O

	I/O	Code	IN 0	IN 1	IN 2	IN 3	IN 4	IN 5	IN 6	IN 7	IN 8	IN 9	OUT 0	OUT 1	OUT 2	OUT 3	OUT 4	OUT 5
Add	dres	ss	2960										2961					
Bit			0	1	2	3	4	5	6	7	8	9	0	1	2	3	4	5
	pu	neral rpose outs	General purpose input 0	General purpose input 1	General purpose input 2	General purpose input 3	General purpose input 4	General purpose input 5	General purpose input 6	General purpose input 7	General purpose input 8	General purpose input 9	-	-	-	-	-	-
		errupt outs	Interrupt input 0	Interrupt input 1	Interrupt input 2	Interrupt input 3	-	-	-	-	-	-	-	-	-	-	-	-
Inputs	res	iick sponse outs	Quick response input 0	Quick response input 1	Quick response input 2	Quick response input 3	-	_	-	-	-	-	-	-	-	-	_	-
lul		ghspeed unters	-	-	High- speed counter 1 (phase- Z/ reset)	High- speed counter 0 (phase- Z/ reset)	_	-	High- speed counter 1 (phase- A, incre- ment, or count in- put)	High- speed counter 1 (phase- B, decre- ment, or direction input)	High- speed counter 0 (phase- A, incre- ment, or count in- put)	High- speed counter 0 (phase- B, decre- ment, or direction input)	-	-	-	-	-	-
	pu	neral- rpose tputs	-	-	-	-		-	-	-		-	General- purpose output 0	General- purpose output 1	General- purpose output 2	General- purpose output 3	General- purpose output 4	General- purpose output 5
S		CW/ CCW outputs	-	-	-	-	-	-	-	-	-		Pulse output 0 (CW)	Pulse output 0 (CCW)	Pulse output 1 (CW)	Pulse output 1 (CCW)	-	-
Outputs	Pulse outputs	Pulse + direction outputs	_	_	-	-	_	-	-	_	_	_	Pulse output 0 pulse)	Pulse output 1 (pulse)	Pulse output 0 (direc- tion)	Pulse output 1 (direc- tion)	-	_
	Pul	Variable duty ratio outputs	_	_	-	-	_	-	-	_	_	_	_	-	-	-	PWM (891) output 0	PWM (891) output 1
Ori		search	Origin search 0 (Origin Input Signal)	Origin search 0 (Origin Proximity Input Signal)	Origin search 1 (Origin Input Signal)	Origin search 1 (Origin Proximity Input Signal)	Origin search 0 (Posi- tioning Com- pleted Signal)	Origin search 1 (Posi- tioning Com- pleted Signal)	-	-	_	_	_	-	_	_	Origin search 0 (Error Counter Reset Output)	Origin search 1 (Error Counter Reset Output)

Note: CJ1M-CPU21 CPU Units have one PWM output only and do not have PWM output 1.

Built-in Input Specifications

Interrupt Inputs and Quick-response Inputs

Item		Specifications
No. of interrupt inputs/ quick-response inputs		4 total
Input	Direct (Input Interrupt) Mode	Execution of an interrupt task is started at the interrupt input's rising or falling edge. Interrupt numbers 140 to 143 are used (fixed). Response time from meeting input condition to start of interrupt task execution: 93 µs min.
interrupts	High-speed Counter Mode	Rising or falling edges of the interrupt are counted using either an incrementing or decrementing counter, and an interrupt task is started when the input count reaches the set value. Interrupt numbers 140 to 143 are used (fixed). I/O response frequency: 1 kHz
Quick-response inputs		Signals that are shorted than the cycle time (30 μs min.) can be read and treated the same as signals that are one for more than one cycle time.

High-speed Counter Inputs

	Item	Specifications							
Number of high-speed counters		2 (High-speed counters 0 and 1)							
Pulse input mode (Selected in PLC Setup)		Differential phase inputs (phase-A, phase-B, and phase-Z input)	e-A, phase-B, and phase-		Increment inputs (increment inputs, reset inputs)				
Response	Line-driver inputs	50 kHz	100 kHz	100 kHz	100 kHz				
frequency	24-V DC inputs	30 kHz	60 kHz	60 kHz	60 kHz				
Counting mode		Linear mode or Ring mode (Select in the PLC Setup.)							

	Item	Specifications				
Count valu	Je	Linear mode: 80000000 to 7FFFFFF hex Ring mode: 00000000 to Ring SV (The Ring SV is set in the PLC Setup and the setting range is 00000001 to FFFFFFF hex.)				
High-speed counter PV storage locations		High-speed counter 0: A271 (leftmost 4 digits) and A270 (rightmost 4 digits) High-speed counter 1: A273 (leftmost 4 digits) and A272 (rightmost 4 digits) Target value comparison interrupts or range comparison interrupts can be executed based on these PVs. Note: The PVs are refreshed in the overseeing processes at the beginning of each cycle. Use the PRV(881) instruction to read the most recent PVs.				
Control	Target value comparison	Up to 48 target values and corresponding interrupt task numbers can be registered.				
method	Range comparison	Up to 8 ranges can be registered, with an upper limit, lower limit, and interrupt task number for each.				
Counter re	eset method	Phase-Z + Software reset: Counter is reset when phase-Z input goes ON while Reset Bit is ON. Software reset: Counter is reset when Reset Bit goes ON. Reset Bits: High-speed Counter 0 Reset Bit is A53100, Counter 1 Reset Bit is A53101.				

Built-in Output Specifications

Position Control and Speed Control

Item	Specifications				
Number of pulse outputs	2 (Pulse output 0 or 1)				
Output frequency	1 Hz to 100 kHz (1-Hz units from 1 to 100 Hz, 10-Hz units from 100 Hz to 4 kHz, and 100-Hz units from 4 to 100 kHz)				
Frequency acceleration and deceleration rates	Set in 1 Hz units for acceleration/deceleration rates from 1 Hz to 2 kHz (every 4 ms). The acceleration and deceleration rates can be set separately only with PLS2(887).				
Changing SVs during instruction execution	e target frequency, acceleration/deceleration rate, and target position can be changed. Changes to the target frequency and celeration/deceleration rate must be made at constant speed.				
Pulse output method	CW/CCW inputs or Pulse + direction inputs				
Number of output pulses	Relative coordinates: 00000000 to 7FFFFFFF hex (Each direction accelerating or decelerating: 2,147,483,647) Absolute coordinates: 80000000 to 7FFFFFFF hex (-2,147,483,648 to 2,147,483,647)				
Instruction used for origin searches and returns	ORIGIN SEARCH (ORG(889)): Origin search and origin return operations according to set parameters				
Instructions used for position and speed control	PULSE OUTPUT (PLS2(887)): Trapezoidal output control with separate acceleration and deceleration rate SET PULSES (PULS(886)): Setting the number of pulses for pulse output SPEED OUTPUT (SPED(885)): Pulse output without acceleration or deceleration (Number of pulses must be set in advance with PULS(886) for position control.) ACCELERATION CONTROL (ACC(888)): Changes frequency or pulse output with acceleration and deceleration MODE CONTROL (INI(880)): Stopping pulse output				
Pulse output PV's storage location	The following Auxiliary Area words contain the pulse output PVs: Pulse output 0: A277 (leftmost 4 digits) and A276 (rightmost 4 digits) Pulse output 1: A279 (leftmost 4 digits) and A278 (rightmost 4 digits) The PVs are refreshed during regular I/O refreshing. PVs can be read to user-specified words with the PRV(881) instruction.				

Variable-duty Pulse Outputs (PWM)

Item	Specifications		
Number of PWM outputs	CJ1M-CPU22/23: 2 (PWM output 0 or 1) CJ1M-CPU21: 1 (PWM output 0)		
Duty ratio	0% to 100%, set in 0.1% units (See note.)		
Frequency	0.1 Hz to 999.9 Hz, Set in 0.1 Hz units.		
Instruction	PULSE WITH VARIABLE DUTY RATIO (PWM(891)): Sets duty ratio and outputs pulses.		

Note: CJ1M CPU Unit Ver. 2.0 or later only. (0% to 100%, set in 1% units for Pre-Ver. 2.0 CPU Units.)

Hardware Specifications

Input Specifications

I	tem	Specifications			
Number of in	nputs	10 inputs			
Input metho	d	24-V DC inputs or line driver (wi	ring changed to select)		
land of the se		24 V DC		Line driver	
input voitage	e specifications	IN0 to IN5	IN6 to IN9	IN0 to IN5	IN6 to IN9
Input voltage	•	20.4 to 26.4 V DCV		RS-422A or RS-422 line driver (conforming to AM26LS31), Pow supply voltage of 5 V $\pm5\%$	
Input impeda	ance	3.6 kΩ 4.0 kΩ $-$		-	
Input curren	t (typical)	6.2 mA 4.1 mA		13 mA	10 mA
Minimum Of	l voltage	17.4 V DC/3 mA min. –		-	
Maximum O	FF voltage	5.0 V DC/1 mA max.			-
Response speed (for	ON response time	Default setting: 8 ms max. (The input time constant can be set to 0 ms, 0.5 ms, 1 ms, 2 ms, 4 ms, 8 ms, 16 ms, or 32 ms in Setup.)			3 ms, 16 ms, or 32 ms in the PLC
general-purpose inputs) OFF response time Default setting: 8 ms max. (The input time constant can be set to 0 ms, 0.5 ms, 1 ms, 2 ms, 4 ms, 8 ms, 16 ms, or 3 setup.)				3 ms, 16 ms, or 32 ms in the PLC	

Input Circuit Configuration

Item	Specifications				
Input	IN0 to IN5	IN6 to IN9			
Circuit configuration	$\begin{array}{c} 3.6 \text{ k}\Omega \\ 24 \text{ V} \\ \hline \\ 100 \Omega \\ \hline \\ 0\text{V/LD-} \\ \hline \\ 100 \Omega \\ \hline \end{array}$	$\begin{array}{c} 24\text{V} \\ \begin{array}{c} 4.0\text{k}\Omega \\ \\ \text{V} \\ \\ \text{LD+} \\ \end{array} \\ \begin{array}{c} 100\Omega \\ \\ \text{N} \\ \\ \end{array} \\ \begin{array}{c} 100\Omega \\ \\ \text{N} \\ \end{array} \\ \begin{array}{c} 100\Omega \\ \\ \end{array} \\ \begin{array}{c} 100$			

General-purpose Output Specifications for Transistor Outputs (Sinking)

Item	Specifications			
Output	OUT0 to OUT3 OUT4 to OUT5			
Rated voltage	5 to 24 V DC			
Allowable voltage range	4.75 to 26.4 V DC			
Max. switching capacity	0.3 A/output; 1.8 A/Unit			
Number of circuits	6 outputs (6 outputs/common)			
Max. inrush current	3.0 A/output, 10 ms max.			
Leakage current	0.1 mA max.			
Residual voltage	0.6 V max.			
ON delay	0.1 mA max.			
OFF delay	0.1 mA max.			
Fuse	None			
External power supply	10.2 to 26.4 V DC 50 mA min.			
Circuit configuration	COM Low voltage volta			

Pulse Output Specifications (OUT0 to OUT3)

Item	Specifications		
Max. switching capacity	30 mA, 4.75 to 26.4 V DC		
Min. switching capacity	7 mA, 4.75 to 26.4 V DC		
Max. output frequency	100 kHz		
Output waveform	OFF 90%		

Unit Versions

Units	Models	Unit version
	CJ1M-CPU12/13	Unit version 4.0
		Unit version 3.0
		Unit version 2.0
CJ1M CPU Units		Pre-Ver. 2.0
		Unit version 4.0
	CJ1M-CPU11/21	Unit version 3.0
		Unit version 2.0

Function Support by Unit Version

Functions Supported for Unit Version 4.0 or Later

CX-Programmer 7.0 or higher must be used to enable using the functions added for unit version 4.0. Additional functions are supported if CX-Programmer version 7.2 or higher is used.

CJ1M CPU Units

		CJ1M	CJ1M-CPU□□		
	Function	Unit version 4.0 or later	Other unit versions		
Online editing of fun-	ction blocks cannot be used for simulations on the CX-Simulator.	ОК	-		
Input-output variables in function blocks OK		OK	-		
Text strings in functi	on blocks	OK	-		
New application instructions	Number-Text String Conversion Instructions: NUM4, NUM8, NUM16, STR4, STR8, and STR16	ОК	_		
instructions	TEXT FILE WRITE (TWRIT)	OK	_		
ST programming in t	ask programs	OK with CX-Programmer version 7.2 or higher	_		
SFC programming in	n task programs	OK with CX-Programmer version 7.2 or higher	-		

User programs that contain functions supported only by CPU Units with unit version 4.0 or later cannot be used on CS/CJ-series CPU Units with unit version 3.0 or earlier. An error message will be displayed if an attempt is made to download programs containing unit version 4.0 functions to a CPU Unit with a unit version of 3.0 or earlier, and the download will not be possible.

If an object program file (.OBJ) using these functions is transferred to a CPU Unit with a unit version of 3.0 or earlier, a program error will occur when operation is started or when the unit version 4.0 function is executed, and CPU Unit operation will stop.

Functions Supported for Unit Version 3.0 or Later

 ${\it CX-Programmer}\ 5.0\ or\ higher\ must\ be\ used\ to\ enable\ using\ the\ functions\ added\ for\ unit\ version\ 3.0.$

CJ1M CPU Units

		CJ1M-CPU□□		
Function		Unit version 3.0 or later	Other unit versions	
Function blocks		OK	-	
Serial Gateway (conve serial port)	erting FINS commands to CompoWay/F commands at the built-in	ОК	-	
Comment memory (in internal flash memory)		ОК	=.	
Expanded simple back	sup data	OK	-	
	TXDU(256), RXDU(255) (support no-protocol communications with Serial Communications Units with unit version 1.2 or later)	ОК	_	
New application instructions	Model conversion instructions: XFERC(565), DISTC(566), COLLC(567), MOVBC(568), BCNTC(621)	ок	-	
	Special function block instructions: GETID(286)	OK	=-	
Additional instruction functions	PRV(881) and PRV2(883) instructions: Added high-frequency calculation methods for calculating pulse frequency. (CJ1M CPU Units only)	ок	-	

User programs that contain functions supported only by CPU Units with unit version 3.0 or later cannot be used on CS/CJ-series CPU Units with unit version 2.0 or earlier. An error message will be displayed if an attempt is made to download programs containing unit version 3.0 functions to a CPU Unit with a unit version of 2.0 or earlier, and the download will not be possible.

If an object program file (.OBJ) using these functions is transferred to a CPU Unit with a unit version of 2.0 or earlier, a program error will occur when operation is started or when the unit version 3.0 function is executed, and CPU Unit operation will stop.

Functions Supported for Unit Version 2.0 or Later

CX-Programmer 4.0 or higher must be used to enable using the functions added for unit version 2.0.

CJ1-H/CJ1M CPU Units

		CJ1M CPU Units			
	Function	CJ1M-CPU	12/13/22/23	CJ1M-CPU11/21	
, .		Unit version 2.0 or later	Other unit versions	Unit version 2.0 or later	
Downloading and Uploading Individual Tasks		ОК	-	ОК	
Improved Read P	rotection Using Passwords	OK	-	ОК	
Write Protection fr CPU Units via Ne	rom FINS Commands Sent to tworks	ОК –		ОК	
Online Network C Tables	connections without I/O	ок	(Supported if I/O tables are automatically generated at startup.)	ок	
Communications Network Levels	through a Maximum of 8	ОК	_	ОК	
Connecting Online	e to PLCs via NS-series PTs	ОК	OK from lot number 030201	ОК	
Setting First Slot Words		OK for up to 64 groups	OK for up to 8 groups	OK for up to 64 groups	
Automatic Transfers at Power ON without a Parameter File		ОК	_	ОК	
	ion of I/O Allocation Method nsfer at Power ON	ОК	-	ОК	
Operation Start/E	nd Times	ОК	-	ОК	
	MILH, MILR, MILC	ОК	-	ОК	
	=DT, <>DT, <dt, <="DT,<br">>DT, >=DT</dt,>	ОК	-	ОК	
	BCMP2	ОК	ОК	ОК	
	GRY	ОК	OK from lot number 030201	OK	
New Application	TPO	ОК	-	OK	
Instructions	DSW, TKY, HKY, MTR, 7SEG	ОК	-	ОК	
	EXPLT, EGATR, ESATR, ECHRD, ECHWR	ОК	-	ОК	
	Reading/Writing CPU Bus Units with IORD/IOWR	ОК	-	ОК	
	PRV2	OK, but only for CPU Units with built-in I/O	-	OK, but only for CPU Units with built-in I/O	

User programs that contain functions supported only by CPU Units with unit version 2.0 or later cannot be used on CS/CJ-series Pre-Ver. 2.0 CPU Units. An error message will be displayed if an attempt is made to download programs containing unit version s.0 functions to a Pre-Ver. 2.0 CPU Unit, and the download will not be possible.

If an object program file (.OBJ) using these functions is transferred to a Pre- Ver. 2.0 CPU Unit, a program error will occur when operation is started or when the unit version 2.0 function is executed, and CPU Unit operation will stop.

Unit Versions and Programming Devices

The following tables show the relationship between unit versions and CX-Programmer versions.

Unit Versions and Programming Devices

	Functions (See note 1.)		CX-Programmer				Duamamina
CPU Unit			Ver. 3.3	Ver. 4.0	Ver. 5.0 Ver. 6.0	Ver. 7.0 or higher	Programming Console
CS/CJ-series unit Ver. 4.0 Functions add for unit version	Functions added	Using new functions	_	-	-	OK (See note 2 and 3.)	
	for unit version 4.0	Not using new functions	ОК	ОК	ОК	ОК	
CS/CJ-series unit	Functions added	Using new functions	-	_	ОК	ОК	No
Ver. 3.0 for unit version	for unit version 3.0	Not using new functions	ОК	ОК	ОК	ОК	restrictions
CS/CJ-series unit Ver. 2.0	Functions added	Using new functions	-	ОК	ОК	ОК	
	for unit version 2.0 Not using	Not using new functions	ОК	ОК	ок	ок	

Note: 1. As shown above, there is no need to upgrade to CX-Programmer version as long as the functions added for unit versions are not used.

- 2. CX-Programmer version 7.1 or higher is required to use the new functionality of CJ1-H-R CPU Units.

 When using CJ1-H-R CPU unit Ver.4.1, use CX-Programmer Ver.7.2 or later (Check the CX-Programmer version in "Version Information").
- 3. CX-Programmer version 7.0 or higher is required to use the functional improvements made for unit version 4.0 of the CS/CJ-series CPU Units. With CX-Programmer version 7.2 or higher, you can use even more expanded functionality.

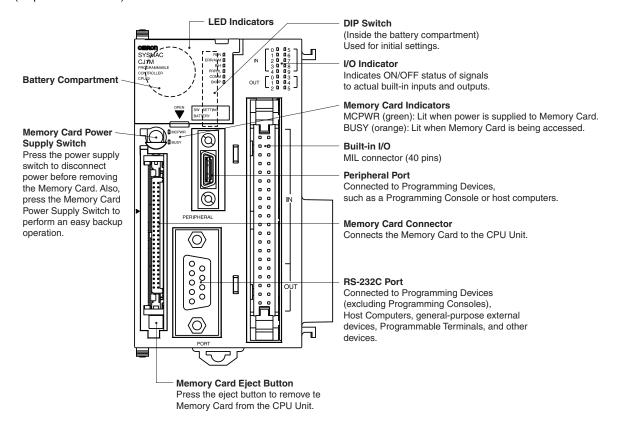
Device Type Setting

The unit version does not affect the setting made for the device type on the CX-Programmer. Select the device type as shown in the following table regardless of the unit version of the CPU Unit.

Series	CPU Unit group	CPU Unit model	Device type setting on CX-Programmer Ver. 4.0 or higher
CJ Series	CJ1M CPU Units	CJ1M-CPU□□	CJ1M

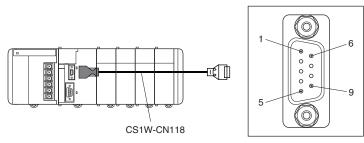
External Interface

A CJ-series CJ1M CPU Unit (with Built-in I/O) provides two communications ports (a peripheral port and an RS-232C port) and one built-in I/O port (40-pin MIL Connector).



Peripheral port

The peripheral port is used to connect a Programming Device (including a Programming Console) or a host computer. It can also be used as an RS-232C port by connecting a suitable cable, such as the CS1W-CN118 or CS1W-CN\u20126. The connector pin arrangement when using a connecting cable for an RS-232C port is shown below.

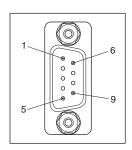


Pin No.	Signal	Name	Direction
1	-	-	-
2	SD (TXD)	Send data	Output
3	RD (RXD)	Receive data	Input
4	RS (RTS)	Request to send	Output
5	CS (CTS)	Clear to send	Input
6	Reserved	None	
7	-	-	-
8	_	-	_
9	SG (0V)	Signal ground	
Connector hood	FG	Protection earth	_

RS-232C Port

Item	Specification
Communications method	Half duplex
Synchronization	Start-stop
Baud rate	0.3/0.6/1.2/2.4/4.8/9.6/19.2/38.4/57.6/115.2 kbps (See note.)
Transmission distance	15 m max.
Interface	EIA RS-232C
Protocol	Host Link, NT Link, 1:N, No-protocol, or Peripheral Bus

Note: Baud rates for the RS-232C are specified only up to 19.2 kbps. The CJ Series supports serial communications from 38.4 kbps to 115.2 kbps, but some computers cannot support these speeds. Lower the baud rate if necessary.



Pin No.	Signal	Name	Direction	
1	FG	Protection earth	-	
2	SD (TXD)	Send data	Output	
3	RD (RXD)	Receive data	Input	
4	RS (RTS)	Request to send	Output	
5	CS (CTS)	Clear to send	Input	
6	5V	Power supply	-	
7	DR (DSR)	Data set ready	Input	
8	ER (DTR)	Data terminal ready	Output	
9	SG (0V)	Signal ground	-	
Connector hood	FG	Protection earth	-	

Note: Do not use the 5-V power from pin 6 of the RS-232C port for anything but the NT-AL001-E Link Adapter.
Using this power supply for any other external device may damage the CPU Unit or the external device.

Built-in I/O MIL connector (40 pins)

Connector Pin Allocations

	Pin layout	Code	Name	Input signal type	Pin No.	*1	Code	Name	Input signal type	Pin No.	*1
			General-purpose input 0 Interrupt input 0 Quick-response input 0 Origin search 0 (Origin Input Signal)	24 V DC	1	A1	IN1	General-purpose input 0 Interrupt input 0 Quick-response input 0 Origin search 0	24 V DC	2	B1
		IN0		LD+	3	A2			LD+	4	B2
				0 V/LD-	5	А3		(Origin Proximity Input Signal)	0 V/LD-	6	ВЗ
		IN2	General-purpose input 2 Interrupt input 2 Quick-response input 2 High-speed counter 1 (Phase-Z/Reset input) Origin search 1 (Origin Input Signal)	24 V DC	7	A4	IN3	General-purpose input 3 Interrupt input 3 Quick-response input 3 High-speed counter 0 (Phase-Z/Reset input) Origin search 1 (Origin Proximity Input Signal)	24 V DC	8	B4
				LD+	9	A 5			LD+	10	B5
_				0 V/LD-	11	A6			0 V/LD-	12	В6
1 · 3 ·	2		General-purpose input 4	24 V DC	13	A7		General-purpose input 5	24 V DC	14	B7
5	─#••#─6	IN4	Origin search 0 (Positioning Completed Signal)	LD+	15	A8	IN5	Origin search 1 (Positioning Completed)	LD+	16	B8
7 · 9 ·	8			0 V/LD-	17	A9		Signal)	0 V/LD-	18	B9
11	12	IN6	General-purpose input 6 High-speed counter 1 (Phase-A, Increment, or Count input)	24 V DC	19	A10		General-purpose input 7 High-speed counter 1 (Phase-B, Decrement, or Direction input)	24 V DC	20	B10
13 · 15 ·	14			LD+	21	A11	IN7		LD+	22	B11
17	17			0 V/LD-	23	A12			0 V/LD-	24	B12
19 · 21 ·	20	IN8	General-purpose input 8 High-speed counter 0 (Phase-A, Increment, or Count input)	24 V DC	25	A13		General-purpose input 9	24 V DC	26	B13
23	23 — 📗 🛚 📙 24			LD+	27	A14	IN9	High-speed counter 0 (Phase-B, Decrement, or	LD+	28	B14
25 · 27 ·	26 28			0 V/LD-	29	A15		Direction input)	0 V/LD-	30	B15
29	OUT0	General-purpose output 0 • In CW/CCW mode: Pulse output 0 (CW) • In Pulse + Direction mode: Pulse output 0 (pulse)	-	31	A16	OUT1	General-purpose output 1 • In CW/CCW mode: Pulse output 0 (CCW) • In Pulse + Direction mode: Pulse output 1 (pulse)	-	32	B16	
	OUT2	General-purpose output 2 • In CW/CCW mode: Pulse output 1 (CW) • In Pulse + Direction mode: Pulse output 0 (direction)	-	33	A17	OUT3	General-purpose output 3 • In CW/CCW mode: Pulse output 1 (CCW) • In Pulse + Direction mode: Pulse output 1 (direction)	-	34	B17	
		OUT4	General-purpose output 4 Origin search 0 (Error Counter Reset Output) PWM(891) output 0	-	35	A18	OUT5	General-purpose output 5 Origin search 1 (Error Counter Reset Output) PWM(891) output 1 *2	-	36	B18
		-	Power supply input (+V) for the output	-	37	A19	-	Not used	-	38	B19
		-	Output COM		39	A20	-	Output COM	-	40	B20

^{*1.} These are the pins on the XW2R-□40G-T Terminal Block. ***2.** PWM(891) output 1 can be used only with the CJ1M-CPU22/CPU23.

Built-in I/O MIL connector Wiring Methods

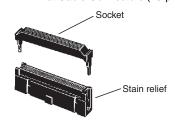
To connect to a Terminal Block, use an OMRON Cable preassembled with the special connector or attach the special connector (sold separately) to a cable yourself.

Using User-made Cables with Connector

Connector Models

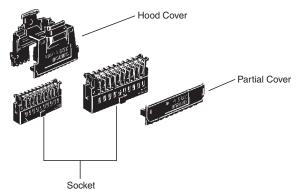
Compatible Connector Specifications

• MIL Flat Cable Connectors (40-pin Pressure-welded Connectors)



Name	OMRON model number	Daiichi Electronics model number	
Socket	XG4M-4030	FRC5-AO40-3TON	
Stain Relief	XG4M-4004	_	
Set model number	XG4M-4030-T	FRC5-AO40-3TOS	
Recommended Flat Cable	XY3A-200□	-	

• MIL Discrete Wire Crimp Connectors (40-pin Pressure-welded Connectors)



	Name	OMRON model number
Olist	AWG 24	XG5M-4032-N
Socket	AWG 28 to 26	XG5M-4035-N
Spare Contacts	AWG 24	XG5W-0031-N
(See note 1.)	AWG 28 to 26	XG5W-0034-N
Hood Cover (See note 2	.)	XG5S-4022
Partial Cover (See note 2) (2 required for each sock		XG5S-2001

Note: 1. Contacts are included with the Socket.

2. Select either the Hood Cover or the Partial Cover.

Wiring

We recommend using cable with wire gauges of AWG 28 to 24 (0.08 to 0.2 mm²). Use a wire with an outer diameter of 1.61 mm max.

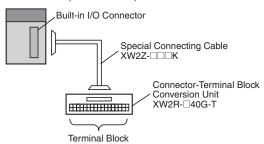
Compatible Terminal Blocks

Recommended Cable	Compatible Terminal Block	Wiring method	Number of terminals	Temperature (°C)	
	XW2R-J40G-T	Phillips screw			
XW2Z-□□□K	XW2R-E40G-T	Slotted screw (rise up)	40	0 to 55	
	XW2R-P40G-T	Push-in spring			

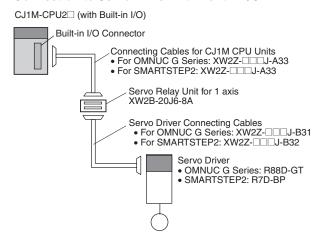
Using an OMRON Cable preassembled with the special connector

Connection to Connector-Terminal Block Conversion Unit with Built-in I/O

CJ1M-CPU2□ (with Built-in I/O)



Connection to Servo Driver with Built-in I/O

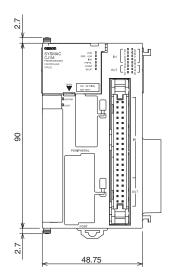


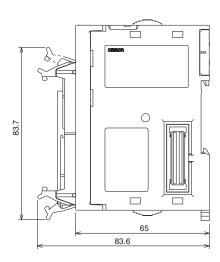
When two axes are used, two Connecting Cables are required at the Servo Driver for each Servo Relay Unit.

Dimensions (Unit: mm)

CJ1M CPU Units (with Built-in I/O) CJ1M-CPU21/22/23







About Manuals

Name	Cat. No.	Contents
SYSMAC CJ/NSJ Series CJ1H-CPU□□H-R, CJ1G-CPU□□, CJ1M-CPU□□, CJ1G-CPU□□P, CJ1G/H-CPU□□H Programmable Controllers Operation Manual	W393	Provides an outlines of and describes the design, installation, maintenance, and other basic operations for the CJ-series PLCs.
SYSMAC CS/CJ/NSJ Series CS1G/H-CPUEV1, CS1G/H-CPUH, CS1D-CPUH, CS1D-CPUS, CJ1H-CPUH-R, CJ1G-CPU, CJ1M-CPU, CJ1G-CPUP, CJ1G/H-CPUH, NSJ(B)-G5D, NSJ(B)-M3D Programmable Controllers Programming Manual	W394	This manual describes programming and other methods to use the functions of the CS/CJ-series and NSJ-series PLCs.
SYSMAC CJ Series CJ1M-CPU21/22/23 Built-in I/O Operation Manual	W395	Describes the functions of the built-in I/O for CJ1M CPU Units.
SYSMAC CS/CJ/NSJ Series CS1G/H-CPUEV1, CS1G/H-CPUH, CS1D-CPUH, CS1D-CPUS, CJ1H-CPUH-R, CJ1G-CPU, CJ1M-CPU, CJ1G-CPUP, CJ1G/H-CPUH, NSJ(B)-G5D, NSJ(B)-M3D Programmable Controllers Instructions Reference Manual	W340	Describes the ladder diagram programming instructions supported by CS/CJ-series and NSJ-series PLCs
SYSMAC CS/CJ Series CQM1H-PRO01-E, C200H-PRO27-E, CQM1-PRO01-E Programming Consoles Operation Manual	W341	Provides information on how to program and operate CS/CJ-series PLCs using a Programming Console.
SYSMAC CS/CJ/NSJ Series CS1G/H-CPU-EV1, CS1G/H-CPU-H, CS1D-CPU-H, CS1D-CPU-S, CJ1G-CPU-H, CJ1M-CPU-C, CJ1G-CPU-P, CJ1G/H-CPU-H, CS1W-SCB-V1, CS1W-SCU-V1, CJ1W-SCU-V1, CP1H-X, CP1H-XA-C-C, CP1H-Y-C-C-C, NSJ	W342	Describes the C-series (Host Link) and FINS communications commands used with CS/CJ-series PLCs.
SYSMAC WS02-CX□□-V□ CX-Programmer Operation Manual	W446	Provides information on how to use the CX-Programmer for all functionality except for function blocks.
SYSMAC WS02-CXDD-VDCX-Programmer Operation Manual Function Blocks (CS1G-CPUDH, CS1H-CPUDH, CJ1G-CPUDH, CJ1H-CPUDH, CJ1M-CPUDH, CJ1M-CPUDH, CJ1M-CPUDH, CP1H-XDDD-D, CP1H-YDDDD-D, CP1H-XDDDD-D, CP1H-XDDDD-D, CP1H-XDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD	W447	Describes the functionality unique to the CX-Programmer Ver. 7.0 and CP-series CPU Units or CS/CJ-series CPU Units with unit version 3.0 or later based on function blocks. Functionality that is the same as that of the CX-Programmer is described in W446 (enclosed).
CXONE-AL□□C-V□/ CXONE-AL□□D-V□ CX-Integrator Operation Manual	W464	Describes operating procedures for the CX-Integrator Network Configuration Tool for CS-, CJ-, CP-, and NSJ-series Controllers.
CXONE-AL□□C-V□/AL□□D-V□ CX-One FA Integrated Tool Package Setup Manual	W463	Installation and overview of CX-One FA Integrated Tool Package.

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Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

Suitability of Use.

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

Programmable Products.

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

Performance Data.

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

<u>Errors and Omissions.</u> <u>Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is accurate.</u> assumed for clerical, typographical or proofreading errors or omissions.

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In the interest of product improvement, specifications are subject to change without notice.

